Barry	Monson	Lecture 2:	Reflection	Groups and	Coxeter	Groups	November	2011
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Seeking Balance: If  $r_{\varphi,a}$ ,  $r_{\psi,b}$  are reflections, and  $\varphi(b) = 0 \neq \psi(a)$ , then  $r_{\psi,b}r_{\varphi,a}r_{\psi,b} = r_{\varphi,c}$ , where  $c = a + \psi(a)b$ . Thus two (conjugate) reflections  $r_{\varphi,a}$  and  $r_{\varphi,c}$  share the same mirror but have independent roots (check this peculiarity).

**Main Concern**: a group  $G \subseteq GL(V)$  generated by a finite set of reflections, typically

 $G = \langle r_j | j \in J \rangle$ , with  $r_j = r_{\varphi_j, a_j}$ , and  $\varphi(a_j) = -2$ .

**Definition**: the reflection group G, with the specified generators  $r_j$ , is balanced if  $\varphi_j(a_k) = 0$ implies  $\varphi_k(a_j) = 0$  for  $j, k \in J$ .

**Examples**: when G contains no transvections, in particular, if G is a group of isometries for some non-singular orthogonal space V.

**Definition**. For G balanced the graph  $\Delta(G)$  has node set J, distinct  $j, k \in J$  are adjacent whenever  $\varphi_j(a_k) \neq 0$ . The  $|J| \times |J|$  matrix  $N := [\varphi_i(a_j)]$  is called a *Cartan matrix* for G (with respect to the specified generating reflections; see [3, §1] for implications when  $\mathbb{K} = \mathbb{R}$ ). **Remark**: By attaching labels to nodes or branches we get Coxeter diagrams  $\Delta_c$  and their various kin.

**Our Standard Setup**:  $J = \{0, \ldots, n-1\}$  and  $\{a_0, \ldots, a_{n-1}\}$  is a basis for V.

**Exercise** (do for sure!) If, as above,  $\{a_0, \ldots, a_{n-1}\}$  is a basis for V, then G acts irreducibly on V if and only if  $\det(N) \neq 0$  and  $\Delta(G)$  is connected.

**Coxeter Groups**. An *abstract Coxeter group*  $\Gamma$  is defined through a special sort of presentation:

$$\Gamma = \langle \rho_0, \dots, \rho_{n-1} : (\rho_i \rho_j)^{p_{ij}} = 1, \quad 0 \leqslant i, j \leqslant n-1 \rangle, \tag{1}$$

where  $p_{ii} = 1$  and  $2 \leq p_{ij} = p_{ji} \leq \infty$  for all  $i \neq j$ . A string Coxeter group has  $p_{ij} = 2$ , equivalently  $\rho_i$  commuting with  $\rho_j$ , whenever  $|i - j| \geq 2$ .

The standard real representation for the Coxeter group  $\Gamma$ : On real *n*-space V, with basis  $a_0, \ldots, a_{n-1}$ , define a symmetric bilinear form  $x \cdot y$  by setting

$$a_i \cdot a_j := -2\cos\frac{\pi}{p_{ij}}, \quad 0 \le i, j \le n-1.$$

Thus  $a_j^2 := a_j \cdot a_j = 2$  and  $r_j(x) = x - (x \cdot a_j)a_j$  is an isometric reflection on V.

**Theorem** (Bourbaki, i.e. Tits?) [2, Ch. 5.3-5.4] The mapping  $\rho_j \mapsto r_j$  induces a faithful representation

$$R: \Gamma \to G := \langle r_0, \ldots, r_{n-1} \rangle$$

of  $\Gamma$  in the orthogonal group O(V).

We may put  $\Gamma$  aside and work instead with the *linear Coxeter group G*. (See [3, 4] for further properties of more general linear Coxeter groups.)

Of course, G is balanced and therefore has a diagram  $\Delta(G)$ , from which we obtain the familiar Coxeter diagram  $\Delta_c(G)$  for G (and for  $\Gamma$ ) as follows: whenever  $p_{ij} \ge 3$  label the branch connecting nodes i, j by  $p_{ij}$ . (If  $p_{ij} = 2$ , nodes i, j are non-adjacent. The very common label 3 is often suppressed.)

**Example**: dihedral groups  $I_2(q)$  of order 2q – symmetry group for q-gon  $\{q\}$ 

**Example**: group  $B_n$  of order  $2^n n!$  for the *n*-cube  $\{4, 3, \ldots, 3\}$ 

**Spherical Cases**:  $G (\simeq \Gamma)$  is finite if-f when  $x \cdot y$  is positive definite ([2, Th. 6.4]). We may call G an orthogonal group generated by reflections or even spherical, since it leaves invariant the unit sphere  $\mathbb{S}^{n-1}$  in V.

Irreducible spherical (hence finite) G ([1]):  $A_n$   $(n \ge 1)$ ,  $B_n$   $(n \ge 2)$ ,  $D_n$   $(n \ge 4)$ ,  $E_n$  (n = 6,7,8),  $F_4$ ,  $H_3$ ,  $H_4$ , or  $I_2(q)$  (dihedral of order 2q).

See Table for Coxeter diagrams; convenient to use same label for group, diagram, root system, depending on your focus.

**Euclidean Cases**:  $x \cdot y$  positive semidefinite, with dim(radV) = 1; G (infinite) is of Euclidean type; acts on affine Euclidean (n-1)-space  $\mathbb{E}^{n-1}$  [2, ch. 4].

**Hyperbolic Cases**:  $x \cdot y$  is non-singular with signature  $(++\ldots+-)$ ; *G* (infinite) is of *hyperbolic type*; acts on hyperbolic (n-1)-space  $\mathbb{H}^{n-1}$  [2, §6.8-6.9].

## References

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